

<b>Summary of lectures <sup>(1)</sup></b>	
<i>Introduction to the course</i>	Data analytics, decision models to limit data misuse. Data types: raw data, dispersions, distributions, time series; types of analysis: descriptive, predictive, prescriptive. Examples of descriptive parameters: mean, median, mode, variance, etc.
<i>Distributions, caveats</i>	How to construct a histogram: Excel frequency function. Density and cumulative distributions. Caveats: statistics vs. probability. Queuing systems, the Waiting Time Paradox. Population vs. sample variance, Bessel's correction. Numerical accuracy and chaotic systems.
<i>Time series</i>	Time series (signals): Fourier transform and anti-transform, limited band signals, Sample Theorem (enunciate).
<i>Time series</i>	Examples of descriptive analytics of time series: cross- and self-correlation. A numerical case: computing self-correlation of a finite/discrete time series via Toeplitz matrix.
<i>Location models</i>	Clustering a dispersion of records: a $p$ -median location model with one decision maker. Single-objective vs. Multi-objective problems. Pareto-optimality. Multiple decision makers with non-converging objectives. Location and pricing problem as a Stackelberg game.
<i>Location models</i>	Formulation of $p$ -median, $p$ -centre, $p$ -(median+centre) problems as integer linear programs. Numerical example, size of solution space.
<i>Optimization problems and models</i>	Definitions: solution feasibility and optimality, problem consistency and unboundedness. Convexity of feasible set. Linear optimization (or LP), geometric vs. analytical description of the feasible set, convex polyhedra. Consistency check: the projection principle.
<i>Optimization problems and models</i>	An example of linear optimization: drawing a convex polyhedron.
<i>Convex polyhedra</i>	Numerical examples.
<i>Convex polyhedra</i>	Affine and linear subspaces, hyperplanes, half-spaces. Special polyhedra: empty set, hyperplane, polyhedral cone. Linear, affine, conic and convex combination. Convex, conic and affine hull. Projection of a polyhedron. Fourier-Veronese Theorem (enunciate only). Examples.
<i>Fourier-Motzkin Method</i>	More numerical examples. Worst case analysis of algorithm complexity.
<i>Duality Theory</i>	From Fourier-Veronese Theorem to the Theorem of the Alternative. Dual (and primal) LP. Weak Duality Theorem. Corollaries. Strong Duality Theorem.
<i>Duality Theory</i>	How to construct the dual of an LP. Numerical examples.
<i>Elements of graph theory</i>	<b>Graphs, directed and undirected. Degree. Regular graphs. Paths, cycles, trees. Connectivity. Handshaking Theorem and Euler Theorem. Eulerian and Hamiltonian graphs.</b>
<i>Duality Theory</i>	Examples of dual problems. Rules for constructing the dual problem. Interpretation of the dual problem. Production optimization and shadow prices. Portfolio optimization and zero-sum games.
<i>Solving LPs</i>	Solving LPs by Fourier-Motzkin Projection Method. Examples: a generic LP, a portfolio optimization problem. Discussion on complexity.
<i>Zero-sum games</i>	Portfolio optimization as a zero-sum game. Dual analysis.
<i>Combinatorial problems</i>	<b>The Transversal problem. 01 LP formulation.</b>
<i>Elements of graph theory</i>	<b>Making a graph Eulerian. An application. Connectivity, forests, trees. Ramsey Theorem. Bipartite graphs and their characterization.</b>
<i>Combinatorial problems</i>	Basic optimization problems on graphs: stable set, clique, transversal, matching, edge-cover, dominating set, coloring. Examples, applications and 01 LP formulations.
<i>Classification in data mining</i>	An example of bad classification. A methodology for building sensible classes (via optimal graph coloring).
<i>Combinatorial problems</i>	Stability, transversal, matching and edge-cover numbers. Primal-dual relations. Edge and clique formulation of the stable set problem. Clique-cover number. Clique and chromatic numbers.

<sup>1</sup> Lectures in black are intended for both courses. Additional lectures in blue are intended for *Optimization Models and Algorithms* only.

<i>Regression</i>	Regression curves in the plane: linear and polynomial regression; generalization. Regression curves in $n$ -dimensional spaces.
<i>Implicit enumeration methods</i>	The curse of dimensionality. Introduction to implicit enumeration: branch-and-bound. Combinatorial optimization and 01 LP, branching by dichotomy. Use of bounds. Numerical example: stable set problem.
<i>Interpolation of efficiency curve</i>	An LP model to interpret the region of non-dominated points. Numerical example in the plane.
<i>Separation</i>	Finding a separating hyperplane: an LP model. An ILP model for separation with a minimum number of outliers.
<i>Matroids and the Greedy Algorithm</i>	Introduction to the Greedy Algorithm. Packing and covering problems. Other combinatorial problems. Two encodings of the Greedy Algorithm. Why does the Greedy Algorithm fail in general?
<i>Implicit enumeration</i>	Numerical example: solving a 01 knapsack problem by branch-and-bound.
<i>Implicit enumeration methods</i>	Branch-and-bound methods. General features: problem partition and use of bounds. Bounds by linear relaxation. Combinatorial bounds, example: TSP and spanning tree bound.
<i>Convex hull of a discrete set</i>	Numerical exercise: compute the implicit form of $conv(S)$ by Fourier-Motzkin projection method.
<i>Overlap</i>	Ways to compute the overlap of two non-separable sets. Use of convex hull. Use of separation hyperplanes.
<i>Separation in 01 LP</i>	Separation of an infeasible solution. Example: TSP. Separation by subtour elimination constraints as a max-flow min-cut problem.
<i>Matroids</i>	Rado's Theorem.
<i>Efficient clustering</i>	Motivation. Tree-clustering. Hierarchical tree-clustering. Applications.
<i>Matroids</i>	Rado's Theorem (enunciate) Consequences of Rado's Theorem, examples. Graphic matroid.
<i>Dynamic programming</i>	Precedence relations and DAGs. Topological ranking. Shortest, longest, safest paths. Levenshtein distance.
<i>Protein design via 01LP</i>	Basics of protein structure: amino-acids and codons. Codon optimization and motif engineering. Dynamic programming vs. 01 LP. Numerical evidence.
<i>VLSI design via 01LP: a tutorial</i>	Boolean functions and PLA. Reducing device area: row compatibility. A combinatorial optimization model.
<i>Matroids and the Greedy algorithm</i>	More matroids: partition matroid, assignment, linear matroid. Representable matroids: graphical as a linear matroid, basic solution of a network flow problem.
<i>Bipartite matching</i>	Matchings and augmenting paths. A combinatorial algorithm for unweighted bipartite matching and its computational complexity. Shortest augmenting paths: extension to the weighted case, complexity.
<i>Matroids and the Greedy algorithm</i>	Examples of application: optimal bidding in constructing a network infrastructure. Two matroid intersection, bipartite matching.
<i>Totally unimodular matrices</i>	Unimodular and totally unimodular matrices. Examples and motivation. Sufficient conditions. Consequences on matching, stable set, transversal and edge-cover problems on bipartite graphs. Non-bipartite matching and odd cycles inequalities. Consecutive one property and stable set/cliqve cover on interval graphs.